D-Style Motor Comparison Chart



- All D-style SmartMotors have a primary RS-232 communications port
- · All D-style SmartMotors have 7 channels 5V TTL non-isolated I/O
- · Optional 10 channels expanded 24VDC isolated I/O
- Dedicated Encoder Out

Peak Torque Continuous Torque

Relative Torque Comparison

NOTE: All torque curves based on 25°C ambient. For ambient temperatures above 25°C, Continuous Torque must be linearly derated to 0% at 85°C.

		SM17205D	SM23165D	SM23165DT	SM23375D	SM23375DT	SM23205D	SM23305D
	in-lb	2.08	2.50	4.61	2.86	5.18	2.96	3.98
Continuous Torque	oz-in	33	40	74	46	83	47	64
John Mada Torquo	N-m	0.24	0.28	0.52	0.32	0.59	0.33	0.45
	in-lb	3.82	4.00	7.40	5.00	9.80	5.03	6.86
	oz-in	61	64	118	80	157	80	110
	N-m	0.43	0.45	0.84	0.57	1.11	0.57	0.77
Nominal Continuous Power	Watts	145	181	204	191	186	226	220
No Load Speed	RPM	7,900	10,400	5,200	8,000	4,000	8,100	5,600
Max. Continuous Current	RPM	6,000	6,500	3,800	6,000	3,250	6,900	4,750
	Amps	3.81	3.545	5.074	5.072	4.52	6.02	5.57
Pools Ossesson	RPM	4,200	6,000	3,500	4,750	2,450	6,000	4,000
Peak Current	Amps	4.69	4.43	5.73	5.829	5.67	8.67	8.18
Voltage Constant	V/krpm	6.506	4.45	9.08	5.62	10.95	6.137	8.873
								0.61
Encoder Resolution	Counts/Rev	4,000	4,000	4,000	4,000	4,000	4,000	4,000
								0.0033
Rotor mertia	10-5 Kg-m2	0.15324	0.6991	0.706	1.342	1.342	1.592	2.344
Weight	lb	1.2	1.0	1.3	2.1	2.2	1.7	2.3
	kg	0.55	0.45	0.59	0.95	0.98	0.79	1.03
								0.250
	mm	5.00	6.35	6.35	6.35	6.35	6.35	6.35
Shaft, Radial Load	lb	7	7	7	7	7	7	7
Shaft, Axial Thrust Load	kg	3.18	3.18	3.18	3.18	3.18	3.18	3.18
								3
Doving Not Ontion	kg	1.36 Yes	1.36 Yes	1.36 Yes	Yes	1.36 Yes	Yes	1.36 Yes
DeviceNet Option		res			res	res	res	res
		Voc	Yes	Yes	Voc	Voc	Voc	Voc
CANopen Option		Yes	Yes	Yes	Yes	Yes	Yes	Yes

Due to the variety of operating conditions and applications for Moog Animatics' products, the end user is solely responsible for making the final selection of the Moog Animatics products and systems based on their own analysis and testing and ensuring that all performance, safety and warning requirements for the application and product are met.

Please consult factory for any supporting hardware and cables needed, full details and latest information.



D-Style Motor Comparison Chart

	SAART O	SMART O	SMART	SMART	SMART .	SMART	SMA CE E	COMBITRONIC TM ROHS ODVA
SM23405D	SM34165D	SM34165DT	SM34205D	SM34305D	SM34405D	SM34505D		
4.88	9.67	12.83	7.91	10.87	12.94	16.34	in-lb	_
78	155	205	126	174	207	261	oz-in	Continuous Torque
0.55	1.09	1.45	0.89	1.23	1.46	1.85	N-m	
8.04	14.12 226	30.00	24.91	34.75	40.38	48.19	in-lb	Dook Townso
0.91	1.60	480 3.39	399 2.81	556 3.93	646 4.56	771 5.44	oz-in N-m	Peak Torque
253	235	615	324	400	438	527	Watts	Nominal Continuous Power
5,300	3,100	5,100	4,500	4,100	3,800	3,300	RPM	No Load Speed
4,500	2,400	4,500	3,750	3,600	3,300	3,100	RPM	May Continuous Cumont
6.76	6.02	16.93	8.28	10.31	11.69	14.37	Amps	Max. Continuous Current
3,900 8.62								Peak Current
9.612	14.98	8.9	10.8	12.1	12.9	14.049	V/krpm	Voltage Constant
0.49	1.72	0.32	0.596	0.490	0.913	0.871	mH	Inductance
4,000	8,000	8,000	8,000	8,000	8,000	8,000	Counts/Rev	Encoder Resolution
0.00439 3.100								Rotor Inertia
2.8	5.0	5.5	3.5	4.5	5.5	6.5	lb	Weight
1.27	2.27	2.49	1.59	2.04	2.49	2.95	kg	**GIGIIL
0.250 6.35								Shaft Diameter
7	15	30	15	15	15	15	lb	Shaft, Radial Load
3.18	6.80	13.61	6.80	6.80	6.80	6.80	kg	Gilait, Naulai LUdu
3 1.36								Shaft, Axial Thrust Load
Yes	Yes	Yes	Yes	Yes	Yes	Yes		DeviceNet Option
	Yes	Yes						PROFIBUS Option
Yes	Yes	Yes	Yes	Yes	Yes	Yes		CANopen Option

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