

BCS RODLESS SCREW DRIVE ACTUATORS

• ENDURANCE TECHNOLOGY •



LINEAR SOLUTIONS MADE EASY

BCS RODLESS SCREW DRIVE ACTUATORS

○ENDURANCE TECHNOLOGY

Endurance Technology features are designed for maximum durability to provide extended service life.

This rodless style actuator is designed for carrying light to moderate loads at an economical price. Based upon our BC2 pneumatic band cylinder, it utilizes a guidance system consisting of an adjustable carrier bracket with two solid bearing rods that transmit the load to the actuator body for superior load support. Built-to-order in stroke lengths up to 3 m [120 inches] with multiple screw options available.

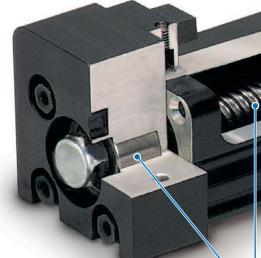
○ADJUSTABLE CARRIER BRACKET ←

- Allows for easy adjustment and replacement of the load bearings throughout the life of the actuator
- Allows customizing the bearing tension and free play of the carrier to meet the applications requirements



• FORMED END CAP WIPERS

 Prevent contaminants from entering the sealing band area to protect internal components



∽LOAD-BEARING CARRIER <u>Design</u>∢

- Engineered resin bearings provide guidance, low friction loss and long life
- Load and moments are transmitted directly to the actuator body



SCREW SUPPORT REARINGS

•High thrust bearing assembly design isolates the motor from axial forces

MULTIPLE SCREW TECHNOLOGIES •

YOU CAN CHOOSE:Solid nuts of bronze or engineered resins offering

engineered resins offering quiet performance at the lowest cost; anti-backlash available

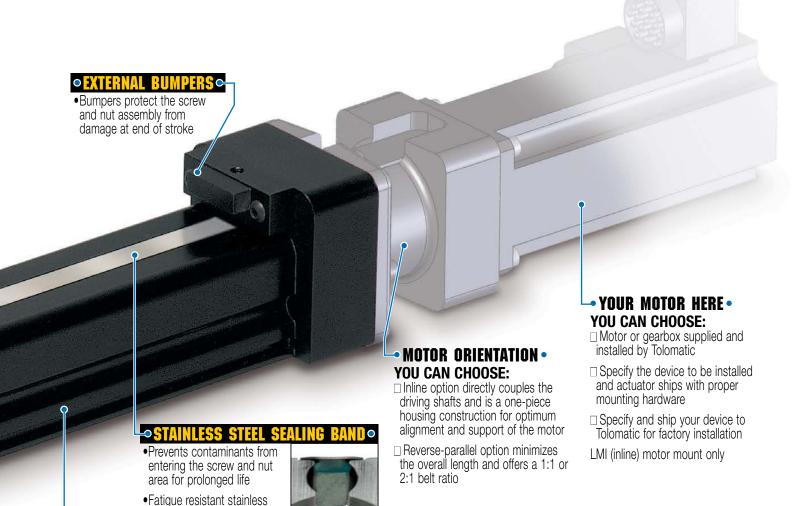
☐ Ball nuts offer positioning accuracy and repeatability with longer life; low-backlash available







TOLOMATIC...LINEAR SOLUTIONS MADE EASY



OLIGHTWEIGHT ALUMINUM DESIGNO

will not elongate

steel bands are specifically made to offer long life and

- •Black anodized extrusion design is optimized for rigidity and strength
- External switch channels on both sides allow easy placement and adjustment of position indicating switches

OPTIONS



CARRIER OPTIONS

□ AUXILIARY CARRIER doubles the load capacity and increases bending moments capacity significantly



☐ **FLOATING MOUNT** compensates for nonparallelism between the actuator and an external support or guidance system



MOUNTING OPTIONS

- SURFACE MOUNT tapped holes are provided on the underside of the actuator heads, as a standard feature, for direct mounting
- ☐ **TUBE SUPPORTS** provide intermediate support of the actuator body throughout long stroke lengths



Provides metric tapped holes for mounting of load to carrier and of actuator to mating surfaces



SWITCHES

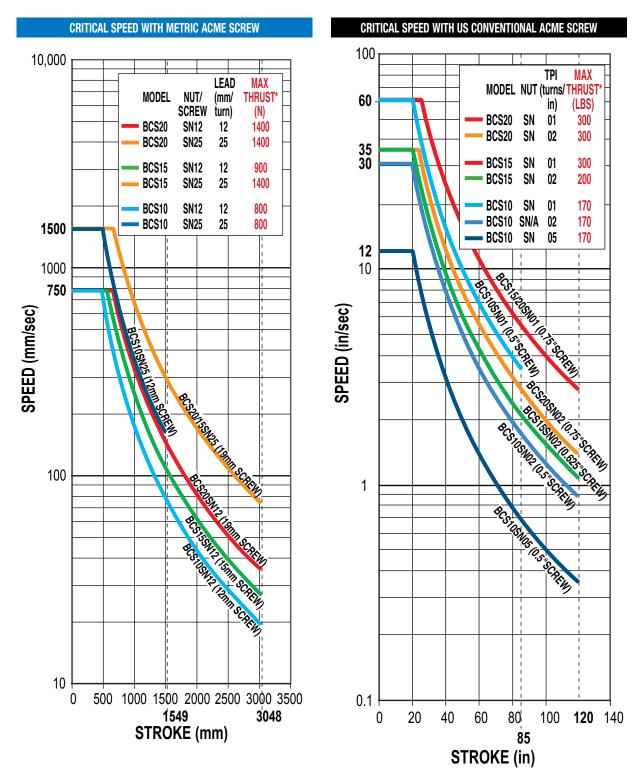
Styles include: reed, hall-effect or triac. Select either 5 m potted cable with flying leads or 150 mm to quick-disconnect coupler with mating 5 m cable.





ACME SCREW/NUT COMBINATIONS

ACME SCREW CRITICAL SPEED CAPACITIES





* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

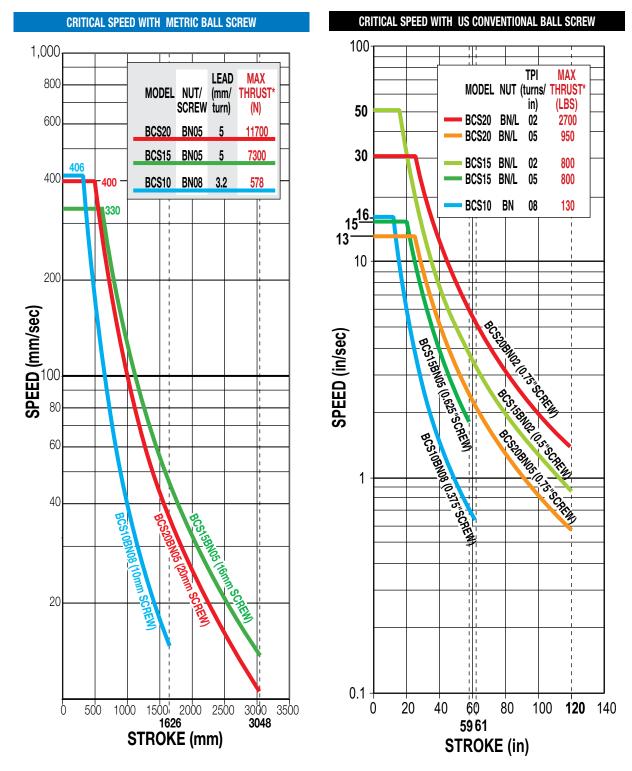
Dotted lines represent maximum stroke for screw selections.

For Screw PV limits, refer to the individual charts located in the technical section for each actuator body size.



BALL SCREW/NUT COMBINATIONS

BALL SCREW CRITICAL SPEED CAPACITIES





* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

Dotted lines represent maximum stroke for screw selections.

Refer to the technical section for each actuator body size for details on life calculations for individual screws.

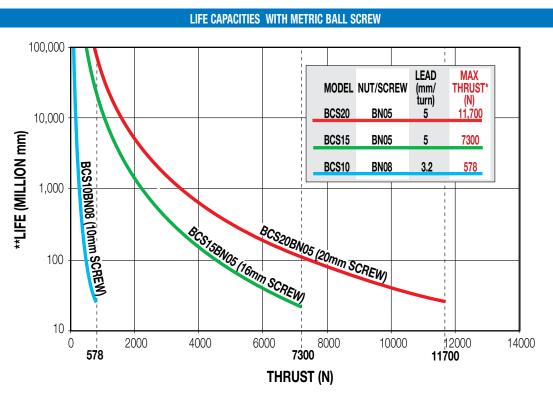


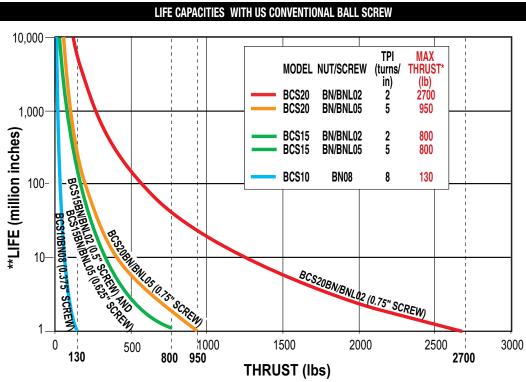


BALL SCREW SPECIFICATIONS



BALL SCREW LIFE CALCULATION







* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

Dotted lines represent maximum thrust for screw selections.

**Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.



SPECIFICATIONS

SPECIFICATIONS RELATED TO ACTUATOR SIZE AND SCREW SELECTION

METRIC LEAD SCREW

	SCREW DIA.	CORPU	LEAD	LEAD	BACKLASH	MAXIMUM	MAXIMUM	INEF	RTIA (kg-m² x	10 ⁻⁶)	BREAKAWAY
ACTUATOR SERIES		SCREW Type		ACCURACY		THRUST*	STROKE	BASE A	CTUATOR	PER/mm	TORQUE
SENIES	(mm)	IIPE	(mm/turn)	(mm/300)	(mm)	(N)	(mm)	In Line	Rev. Parallel	OF STROKE	(N-m)
	10	BN	3.2	0.13	0.38	578	1549	31.94	37.50	3.472	0.11
BCS10	10	BNL	3.2	0.13	0.05	578	1549	31.94	67.50	3.472	0.11
розто	12	SN	12	0.13	0.18	800	3048	4.53	5.18	0.410	0.20
	12	SN	25	0.13	0.18	800	1626	8.34	8.98	0.410	0.28
	15	SN	12	0.13	0.18	900	3048	13.22	14.83	0.966	0.27
BCS15	16	BN	5	0.13	0.38	7300	1499	13.69	15.77	1.258	0.16
БСЭТЭ	16	BNL	5	0.13	0.05	7300	1499	13.69	15.77	1.258	0.16
	19	SN	25	0.13	0.18	1400	3048	39.98	44.17	2.517	0.32
	19	SN	12	0.13	0.18	1400	3048	35.42	39.28	2.517	0.39
BCS20	19	SN	25	0.13	0.18	1400	3048	50.95	54.81	2.517	0.57
DU320	20	BN	5	0.13	0.38	11700	3048	38.61	43.32	3.102	0.25
	20	BNL	5	0.13	0.05	11700	3048	38.61	43.32	3.102	0.25

US CONVENTIONAL LEAD SCREWS

	SCREW DIA.		TPI	LEAD	BACKLASH	MAXIMUM	MAXIMUM	I	NERTIA (lb-in ²	²)	BREAKAWAY
ACTUATOR Series		SCREW Type	ırı	ACCURACY	DAUNLASII	THRUST*	STROKE	BASE A	CTUATOR	PER/in	TORQUE
	(in)		(turns/in)	(in/ft)	(in)	(lb)	(in)	In Line	Rev. Parallel	OF STROKE	(lb-in)
	0.375	BN	08	0.004	0.015	130	61	0.0046	0.0054	0.0005	1.000
	0.375	BNL	08	0.004	0.002	130	61	0.0046	0.0054	0.0005	1.000
BCS10	0.500	SN	01	0.006	0.007	170	85	0.0321	0.0348	0.0017	1.857
розто	0.500	SN	02	0.005	0.007	170	120	0.0190	0.0217	0.0017	1.563
	0.500	SNA	02	0.005	0.003	170	120	0.0190	0.0217	0.0017	1.563
	0.500	SN	05	0.006	0.007	170	120	0.0153	0.0180	0.0017	1.125
	0.500	BN	02	0.003	0.015	800	59	0.0299	0.0327	0.0017	1.375
	0.500	BNL	02	0.003	0.002	800	59	0.0299	0.0327	0.0017	1.375
BCS15	0.625	BN	05	0.003	0.015	800	59	0.0455	0.0524	0.0042	1.188
розіз	0.625	BNL	05	0.003	0.002	800	59	0.0455	0.0524	0.0042	1.188
	0.625	SN	02	0.005	0.007	200	120	0.0558	0.0627	0.0042	1.563
	0.750	SN	01	0.005	0.007	300	120	0.1391	0.1536	0.0087	2.188
	0.750	BN	02	0.004	0.015	2700	120	0.1241	0.1374	0.0087	1.750
	0.750	BNL	02	0.004	0.002	2700	120	0.1241	0.1374	0.0087	1.750
BCS20	0.750	BN	05	0.003	0.015	950	120	0.1091	0.1224	0.0087	1.563
DUJZU	0.750	BNL	05	0.003	0.002	950	120	0.1091	0.1224	0.0087	1.563
	0.750	SN	01	0.005	0.007	300	120	0.1775	0.1908	0.0087	3.125
	0.750	SN	02	0.005	0.007	300	120	0.1241	0.1374	0.0087	2.188

SCREW CODE DESCRIPTION

SN Solid Nut

SNA Anti-backlash Solid Nut

BN Ball Nut

BNL Low-Backlash Ball Nut



Contact Tolomatic for higher accuracy and lower backlash options.

* For Acme screws, maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

For ball screws, maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.



ACTUATOR SIZING

SPECIFICATIONS

GENERAL ACTUATOR SPECIFICATIONS

	METRIC ACTUATORS										
ACTUATOR SERIES	CARRIER WEIGHT (kg)	BASE WEIGHT (kg) (Including Carrier)	WEIGHT PER/IN OF STROKE (g)	TEMPERATURE Range (C°)	IP RATING**						
BCS10	0.31	1.32	3.1	4 - 54	44						
BCS15	0.88	2.90	7.0	4 - 54	44						
BCS20	1.27	6.62	11.9	4 - 54	44						

	US CONVENTIONAL ACTUATORS										
1	CTUATOR CARRIER BASE WEIGHT (Ib) (Including OF STROKE (Ib) RANGE (F°)										
BC	S10	0.69	2.91	0.176	40 - 130	44					
BC	S15	1.94	6.61	0.392	40 - 130	44					
BC	S20	2.81	14.59	0.666	40 - 130	44					

BCS CARRIER BRACKET BOLT ADJUSTMENT (ALL SIZES)



BCS carrier bracket adjustment bolts should be adjusted to suit each individual application, depending on the degree of rigidity required. A good starting point is to tighten the nut on the bolt until there is no lateral movement of the bolt. Then,

equally tighten each nut on the carrier bolt while moving the carrier by hand along the length of the stroke. When all lateral play in the carrier is eliminated and free movement along the length of the stroke is maintained, your carrier bracket is adjusted properly. Some applications may require fine tuning of this adjustment to gain more lateral play or a higher degree of rigidity. In demanding applications, carrier adjustments should be done periodically.



* CAUTION:

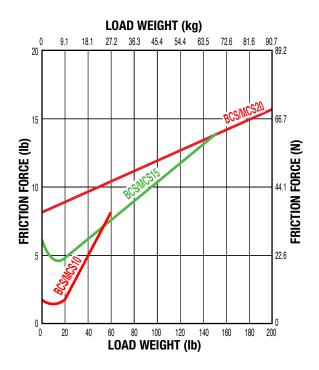
Over-tightening increases drive torque of motor and drive.



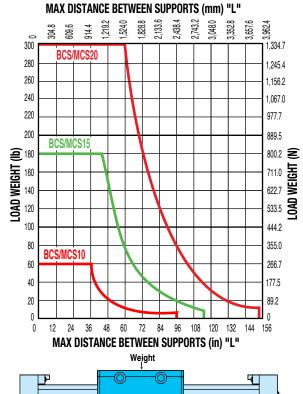
- Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact Tolomatic.
- ** Protected against ingress of solid particles greater than 1mm (.039 in) and splashing water

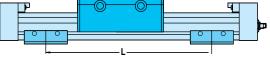
LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

FRICTION FORCE



SUPPORT RECOMMENDATIONS







SPECIFICATIONS

DYNAMIC BENDING MOMENTS AND LOADS

	MAXIMUM BENDING MOM	ENTS AND LOADS		METRIC		US C	ONVENTIO	NAL
STANDARD CARRIER			BCS10	BCS15	BCS20	BCS10	BCS15	BCS20
Fz 1	Mx Moment (Roll)	(N-m : lb-in)	6.2	31.1	33.9	55	275	300
My Mz	My Moment (Pitch)	(N-m : lb-in)	11.3	56.5	124.3	100	500	1100
Mx Z	Mz Moment (Yaw)	(N-m : lb-in)	3.4	22.6	36.7	30	200	325
	Fz Moment (Lateral)	(N : lb)	267	801	1335	60	180	300
AUXILIARY CARRIER: Increases rigidity, lo	oad-carrying capacity and n	noments	BCS10	BCS15	BCS20	BCS10	BCS15	BCS20
Fz ‡	Mx Moment (Roll)	*(N-m : lb-in)	12.4	62.1	67.8	110	550	600
My	My Moment (Pitch)	*(N-m : lb-in)	32.4	164.1	274.6	287	1453	2430
Mx	Mz Moment (Yaw)	*(N-m : lb-in)	32.4	164.1	274.6	287	1453	2430
"D"	Fz Moment (Lateral)	(N : lb)	534	1602	2670	120	360	600
	Minimum Dimension 'D'	(mm : in)	129.5	165.0	206.0	5.10	6.50	8.10



Please see BCS Carrier Bracket Bolt Adjustment on page BCS 6

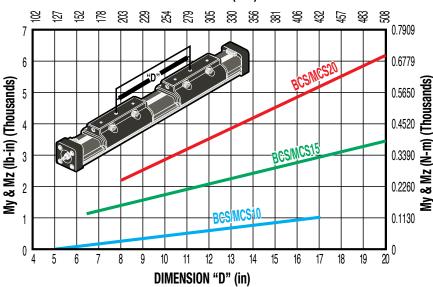


Breakaway torque will increase when using the Auxiliary carrier option. When ordering, determine your working stroke and enter this value into the configuration string. Overall actuator length will automatically be calculated.

*Loads shown in table are at minimum "D" dimension, for ratings with longer "D" dimension see graph below.

AUXILIARY CARRIER: BENDING MOMENT AT 'D' DISTANCE

DIMENSION "D" (mm)



Rates shown on charts were calculated with these assumptions:

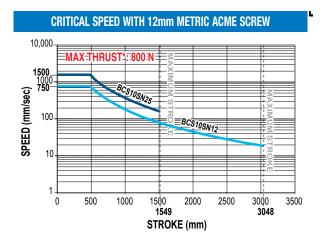
- 1.) Coupling between carriers is rigid.
- 2.) Load is equally distributed between carriers.

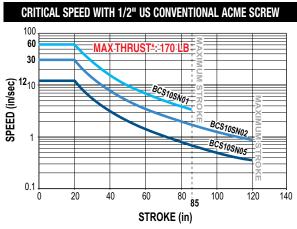
- 3.) Coupling device applies no misalignment loads to carriers.
- * Customer must specify Dimension "D" (Distance between carrier center lines) in configuration string.

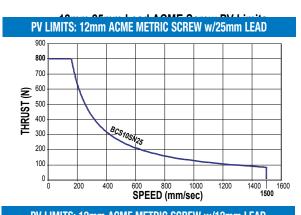


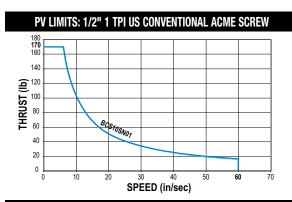
ACME SCREW SPECIFICATIONS

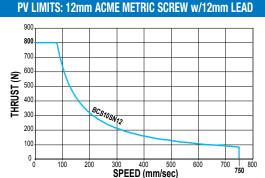
BCS10 ACME SCREW CRITICAL SPEED AND PV LIMITS



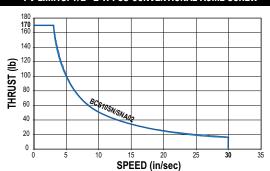






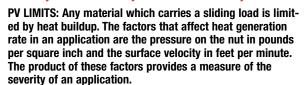


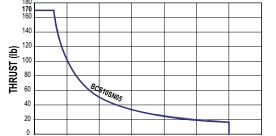
PV LIMITS: 1/2" 2 TPI US CONVENTIONAL ACME SCREW





* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.





SPEED (in/sec)

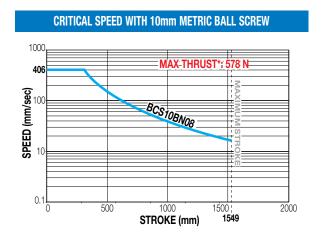
PV LIMITS: 1/2" 5 TPI US CONVENTIONAL ACME SCREW

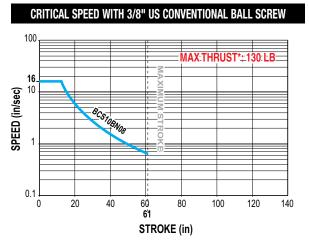




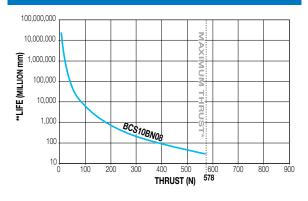
BALL SCREW SPECIFICATIONS

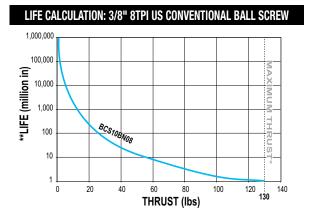
BCS10 BALL SCREW SPECIFICATIONS





LIFE CALCULATION: 10mm METRIC BALL SCREW w/3.2mm LEAD





BN = Ball Nut



* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

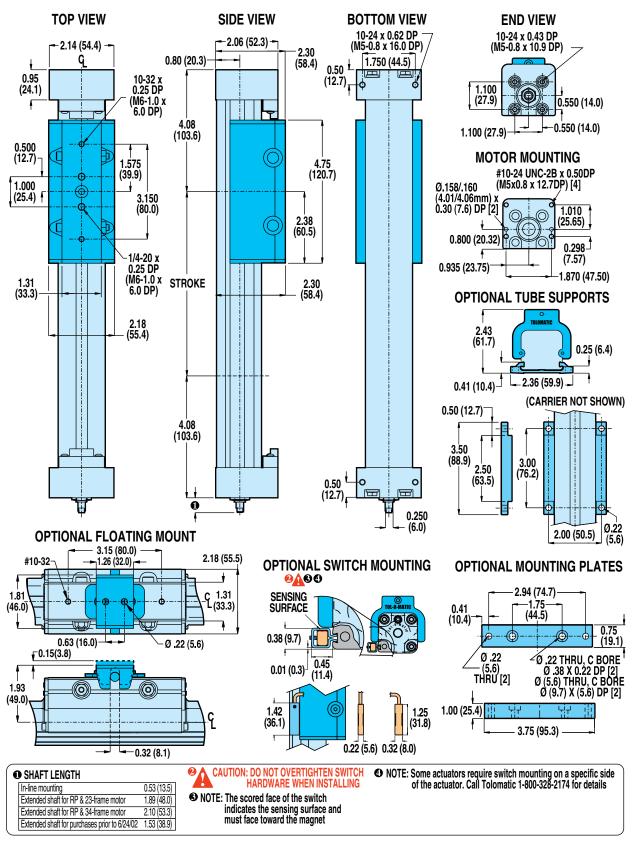
**Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

DIMENSIONS

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS10 ACTUATOR AND OPTIONS



Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

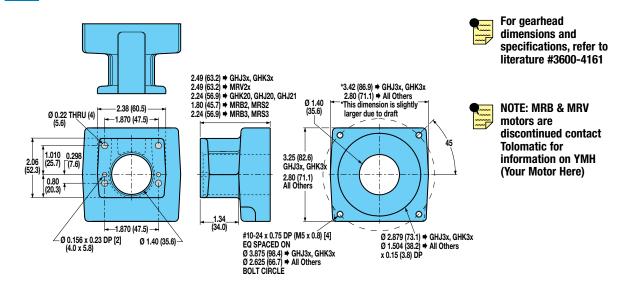


DIMENSIONS

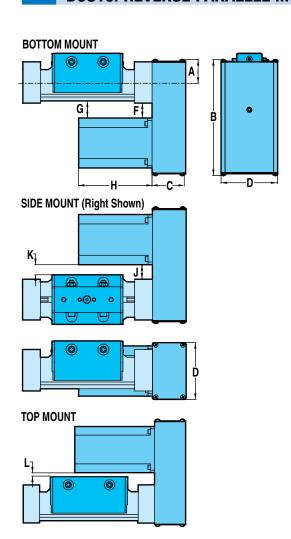
3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS10: IN-LINE MOUNT FOR MOTORS OR GEARHEADS



BCS10: REVERSE PARALLEL MOUNTING



SPECIFICATIONS

	REDU	HT OF CTION IVE	REDUCTION INERTIA AT MOTOR SHAFT			
	1:1	2:1	1:1	2:1		
	kg	kg	kg-cm ²	kg-cm ²		
NEMA 23 Frame	0.9344	0.9344	0.2043	0.2767		

	RED	GHT OF UCTION RIVE	REDUCTION INERTIA AT MOTOR SHAFT			
	1:1	2:1	1:1	2:1		
	lbs	lbs	lb-in ²	lb-in ²		
NEMA 23 Frame	2.06	2.06	0.070	0.095		

REDUCTION EFFICIENCY: 0.95

DIMENSIONS

		A	В	C	D	F	G		*H	J	K	L
		mm	mm	mm	mm	mm	mm	Size	mm	mm	mm	mm
2	3 (21	120.7			
{	H E	26.6	176.7	510	026	<i>15</i> 0	16 5	22	146.1	20 1	16 5	28.2
1	<u> </u>	30.0	170.7	54.0	02.0	40.9	40.5	23	146.1 171.5	39.1	40.5	20.2
2	Z —							24	196.9			

	Α	В	C	D	F	G		*H	J	K	L
	in.	in.	in.	in.	in.	in.	Size	in.	in.	in.	in.
co .							21	4.75			
A Z	4 44	C 0C	0 10	2 05	4 04	1 00	22	5.75	4 5 4	1 00	
I S	1.44	6.96	2.13	3.25	1.81	1.83	23	6.75	1.54	1.83	1.11
Z _							24	7.75			

^{*}H: Typical Motor Length

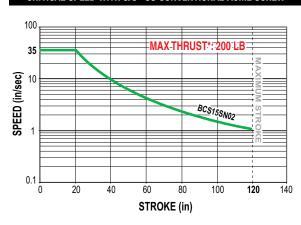




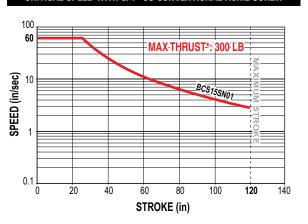
ACME SCREW SPECIFICATIONS

BCS15 US CONVENTIONAL ACME SCREW SPECIFICATIONS

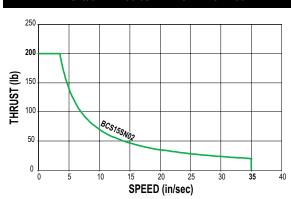
CRITICAL SPEED WITH 5/8" US CONVENTIONAL ACME SCREW



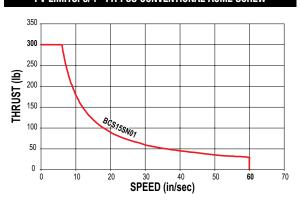
CRITICAL SPEED WITH 3/4" US CONVENTIONAL ACME SCREW



PV LIMITS: 5/8" 2TPI US CONVENTIONAL ACME SCREW



PV LIMITS: 3/4" 1TPI US CONVENTIONAL ACME SCREW



SN = Solid Nut

SNA = Solid Anti-backlash Nut



* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

PV LIMITS: Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

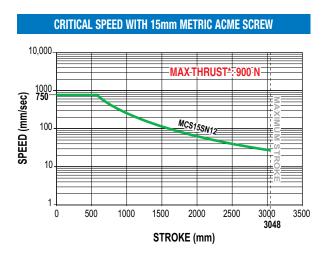
$$\frac{P}{\left(\frac{Thrust}{(Max.\ Thrust\ Rating)}\right)}~\chi~\frac{V}{\left(\frac{Speed}{(Max.\ Speed\ Rating)}\right)}~\leq~0.1$$

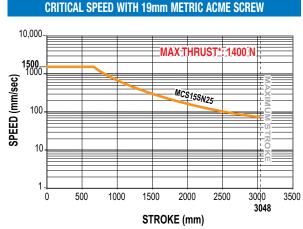




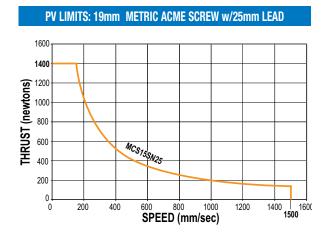
ACME SCREW SPECIFICATIONS

BCS15 METRIC ACME SCREW SPECIFICATIONS





PV LIMITS: 15mm METRIC ACME SCREW w/12mm LEAD 1000 900 THRUST (newtons) 700 600 500 400 MCS15SN12 300 200 100 0 100 200 400 SPEED (mm/sec)



SN = Solid Nut



* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

PV LIMITS: Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

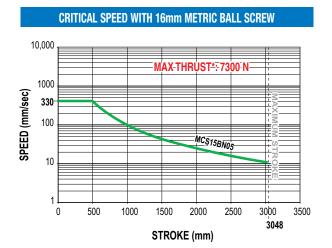


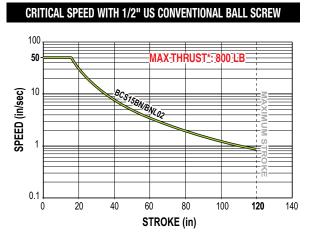




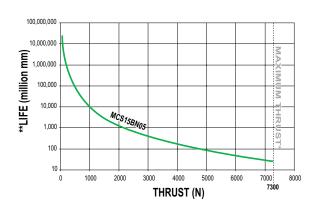
BALL SCREW SPECIFICATIONS

BCS15 BALL SCREW SPECIFICATIONS

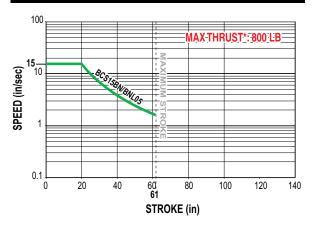




LIFE CALCULATION: 16mm METRIC BALL SCREW w/5mm LEAD



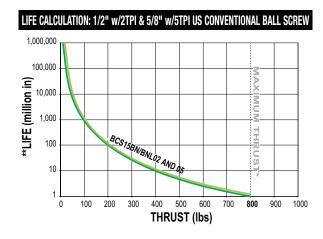
CRITICAL SPEED WITH 5/8" US CONVENTIONAL BALL SCREW



BN = Ball Nut BNL = Ball Nut with Low-Backlash



- * Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.
- **Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

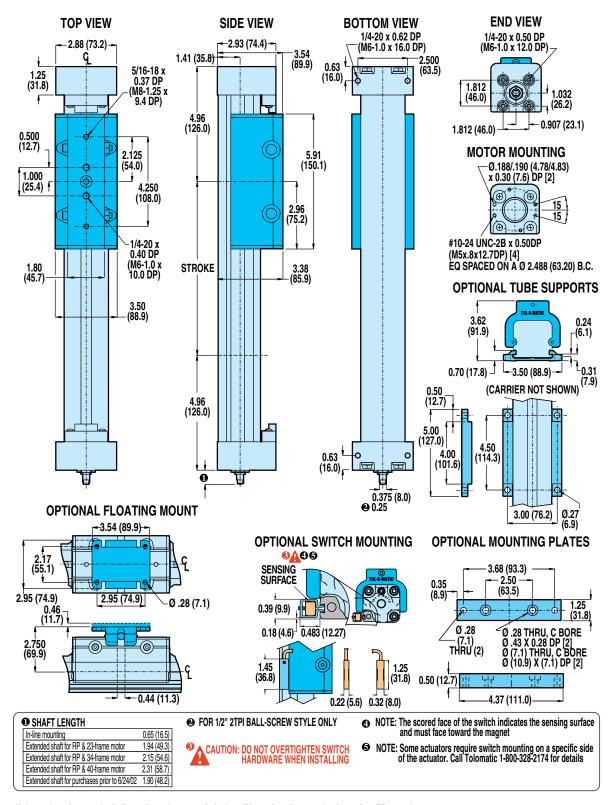


DIMENSIONS

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS15 ACTUATOR AND OPTIONS



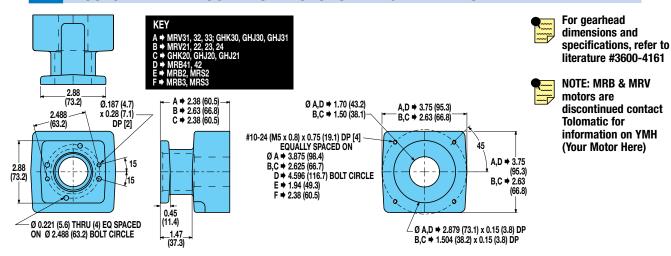
Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

DIMENSIONS

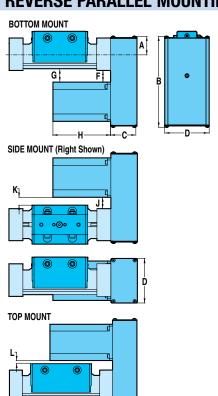
3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS15: IN-LINE MOUNT FOR MOTORS AND GEARHEADS



BCS15: REVERSE PARALLEL MOUNTING



SPECIFICATIONS

	REDU	HT OF CTION IVE	REDUCTION INERTIA AT MOTOR SHAFT			
	1:1	2:1	1:1	2:1		
	kg	kg	kg-cm ²	kg-cm ²		
NEMA 23 Frame	0.9843	1.0886	0.2043	0.2767		
NEMA 34 Frame	1.1839	1.2882	0.2043	0.2767		

	RED	GHT OF Uction Rive	REDUCTION INERTIA AT MOTOR SHAFT			
	1:1	2:1	1:1	2:1		
	lbs	lbs	lb-in ²	lb-in ²		
NEMA 23 Frame	2.17	2.40	0.070	0.095		
NEMA 34 Frame	2.61	2.84	0.070	0.095		

REDUCTION EFFICIENCY: 0.95

DIMENSIONS

	A	В	C	D	F	G		H*	J	K	L
	mm	mm	mm	mm	mm	mm	Size	mm	mm	mm	mm
က							21	120.7			
A 2	20.0	100 1	E40	00.0	10.0	17.0	22 23	146.1	10 1	17.0	05.0
NEMA 23 Frame	30.0	189.4	34.0	82.0	43.2	47.0	23	171.5 42.4	47.2	25.3	
z					24 196.9						
34 e							31	155.2			
NEMA 34 Frame	53.8	206.6	60.3	101.6	26.7	30.7	32	186.9	25.9	30.7	8.9
FE.							33	218.7			

		Α	В	C	D	F	G		H*	J	K	L
		in.	in.	in.	in.	in.	in.	Size	in.	in.	in.	in.
ſ	3							21	4.75			
ı	A 2 me	1 11	7.46	0 10	2 25	1 70	1 05	22	5.75	1 67	1 00	0.00
	NEMA 23 Frame	1.44	7.40	2.13	3.23	1.70	1.00	23	6.75	1.07	1.86	0.90
	Z –							24	7.75			
	34 e	- a			4.00	1.05	1.21	31	6.11			
ı	NEMA 34 Frame	2.12	8.14	2.38				32	7.36	1.02	1.21	0.33
	빌드							33	8.61			

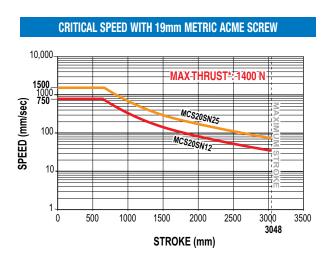
*H: Typical Motor Length

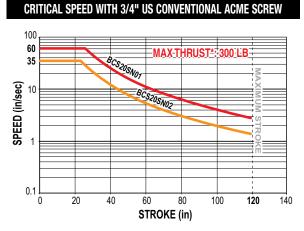


ACME SCREW SPECIFICATIONS

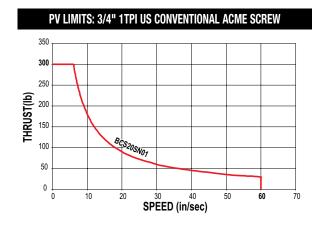


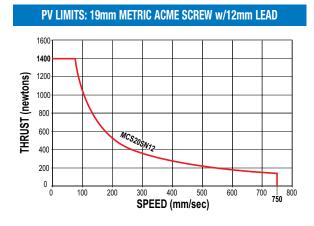
BCS20 ACME SCREW SPECIFICATIONS



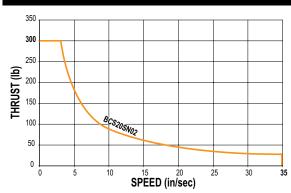


PV LIMITS: 19mm METRIC ACME SCREW w/25mm LEAD 1600 1400 1200 THRUST (newtons) 1000 800 600 MCS20SN25 400 200 200 400 1400 1600 1500 800 1000 1200 SPEED (mm/sec)





PV LIMITS: 3/4" 2TPI US CONVENTIONAL ACME SCREW



SN = Solid Nut SNA = Solid Anti-backlash Nut

* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

PV LIMITS: Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

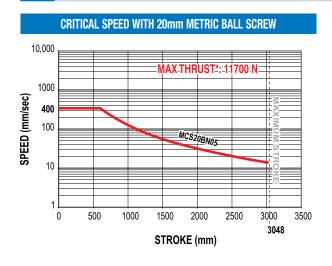


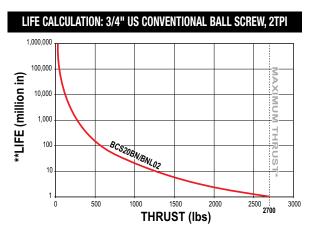




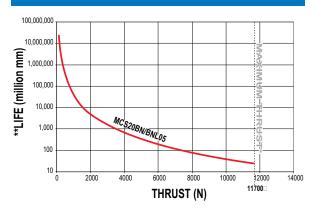
BALL SCREW SPECIFICATIONS

BCS20 BALL SCREW SPECIFICATIONS

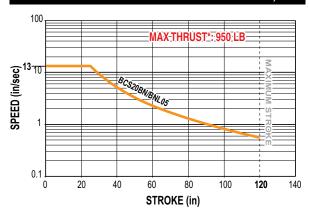




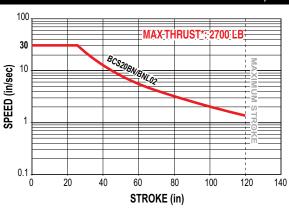
LIFE CALCULATION: 20mm METRIC BALL SCREW w/5mm LEAD



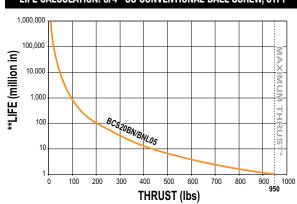
CRITICAL SPEED WITH 3/4" US CONVENTIONAL BALL SCREW, 5TPI



CRITICAL SPEED WITH 3/4" US CONVENTIONAL BALL SCREW, 2TPI



LIFE CALCULATION: 3/4" US CONVENTIONAL BALL SCREW, 5TPI



BN = Ball Nut BNL = Ball Nut with Low-Backlash



Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

**Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

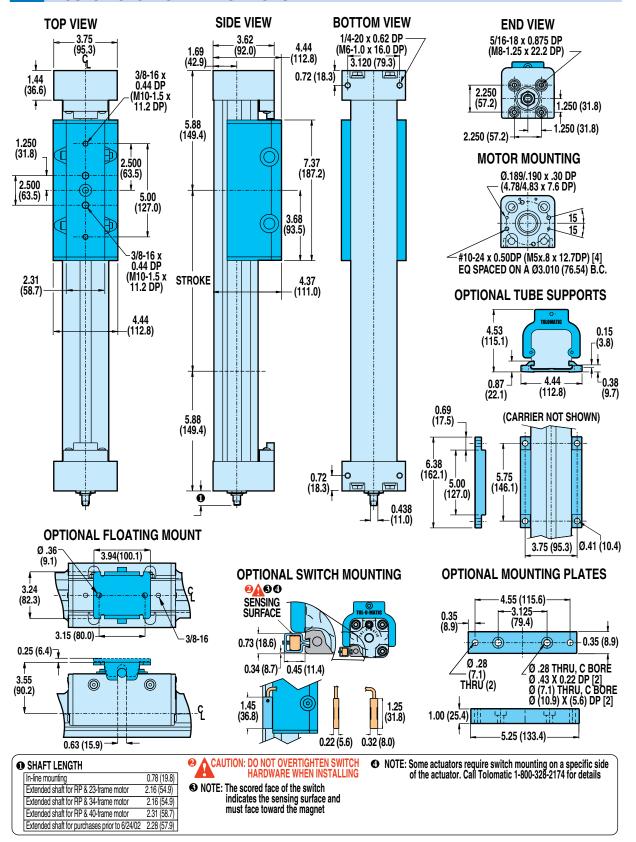


DIMENSIONS

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS20 ACTUATOR AND OPTIONS



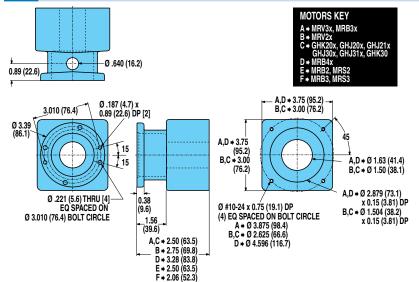
Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

DIMENSIONS

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions



BCS20: IN-LINE MOUNT FOR MOTORS AND GEARHEADS



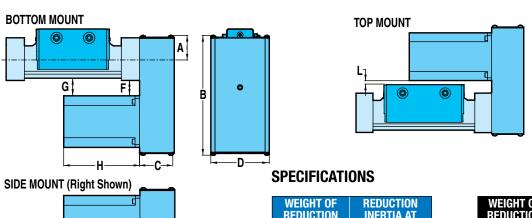


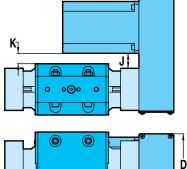
For gearhead dimensions and specifications, refer to literature #3600-4161



NOTE: MRB & MRV motors are discontinued contact **Tolomatic for** information on YMH (Your Motor Here)

BCS20: REVERSE PARALLEL MOUNTING





	REDU	HT OF CTION IVE	REDU INERT MOTOR	IA AT		WEIG Redu Dr	CTION	REDUCTION INERTIA AT MOTOR SHAFT		
	1:1 2:1		1:1	2:1		1:1	2:1	1:1	2:1	
	kg	kg	kg-cm ²	kg-cm ²		lbs	lbs	lb-in ²	lb-in ²	
NEMA 23 Frame	1.41	1.48	0.3447	0.2928	NEMA 23 Frame	3.11	3.27	0.118	0.100	
NEMA 34 Frame	1.44	1.51	0.3447	0.2928	NEMA 34 Frame	3.18	3.34	0.118	0.100	

REDUCTION EFFICIENCY: 0.95

DIMENSIONS

	Α	В	C	D	F	G		H*	J	K	L		Α	В	C	D	F	G		H*	J	K	L						
	mm	mm	mm	mm	mm	mm	Size	mm	mm	mm	mm		in.	in.	in.	in.	in.	in.	Size	in.	in.	in.	in.						
က							21	120.7			EMA 23		က	A 23	A 23										21	4.75			
A 2	26.6	226 F	60.2	1016	61.0	CO E	22	146.1	<i>57.</i> 0	GE O		A Z				01 000 400	00 2.44	م دم	22	5.75	2.25	0.56	1 20						
NEMA 23 Frame	30.0	236.5	00.3	101.0	01.0	03.3	23	171.5	37.2	03.0		1.44 9.31	.44 9.31 1	4 9.31 2.30	.31 2.30 4.	36 4.00		2.50	23	6.75	2.23	2.30	1.38						
Z							24	196.9				Z							24	7.75									
34 e							31	155.2			8 18.5 WA 34	34 e	MA 34 ame 1.96						31	6.11									
NEMA 34 Frame	49.7	249.6	60.3	101.6	45.5	47.2	32	186.9	40.9	48.8		NEMA Fram		1.96	1.96	1.96 9	1.96 9.83	9.83 2.38	38 4.00	1.79	1.86	32	7.36	7.36 1.61 1.92 0.	0.73				
F F							33	218.7				F F							33	8.61									

*H: Typical Motor Length



SWITCHES



There are 10 sensing choices: DC reed, form A (open) or form C (open or closed); AC reed (Triac, open); Hall-effect, sourcing, PNP (open); Hall-effect, sinking, NPN (open); each with either flying leads or QD (quick disconnect). Commonly used to send analog signals to PLC (programmable logic controllers), TLL, CMOS circuit or other controller device. These switches are activated by the actuator's magnet.

Switches contain reverse polarity protection. QD cables are shielded; shield should be terminated at flying lead end.

If necessary to remove factory installed switches, be sure to reinstall on the same of side of actuator with scored face of switch toward internal magnet.

SPECIFICATIONS

		REE	D DC		REE	D AC	HALL-EFFECT DC				
ORDER CODE	RT	RM	BT	BM	CT	CM	TT	TM	KT	KM	
LEAD	5m	QD*	5m	QD*	5m	QD*	5m	QD*	5m	QD*	
CABLE SHIELDING	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	
SWITCHING LOGIC	"A" Norm	nally Open	"C" Normally (Open or Closed	Triac Norr	nally Open	PNP (Sourcii Op		NPN (Sinking) Normally Ope		
MECHANICAL CONTACTS	Single-Pole S	Single-Throw	Single-Pole [Double-Throw	Single-Pole	Single-Throw	NO,	These Are Solid	d State Compon	ents	
COIL DIRECT	Ye	es	Y	es	Y	es			_		
POWER LED	None		No	one	No	None			None		
SIGNAL LED	Ticu L	TOL-O-MATIC					Red TOL-O-MATIC Red TOL-O-MATIC				
OPERATING VOLTAGE	200 Vo	dc max.	120 Vdc max.		120 Va	ac max.	5 - 25 Vdc				
OUTPUT RATING			_		-	_	25 Vdc, 200mA dc				
OPERATING TIME		ec max. g bounce)	0.7 msec max. (including bounce)		_		< 10 micro sec.				
OPERATING TEMPERATURE			-40°F [-40°C]	to 158°F [70°C]			0°F [-18°C] to 150°F [66°C]				
RELEASE TIME		1.0 ms	ec. max.		-	_	_				
ON TRIP POINT					_		150 Gauss maximum				
OFF TRIP POINT		_			-	_	40 Gauss minimum				
**POWER RATING (WATTS)	10.	.0 §		3.0 § §		10.0		5.0			
VOLTAGE DROP	2.6 V typical at 100 mA NA			IA .	-	_	_				
RESISTANCE		0.1 Ω Ini	tial (Max.)		_	_	_				
CURRENT CONSUMPTION	_				1 Amp at 86°F [30°C]	0.5 Amp at 140°F [60°C]	200 mA at 25 Vdc				
FREQUENCY		_			47 - 63 Hz —						
CABLE MIN. STATIC	0.630" [16mm]										
BEND RADIUS DYNAMIC					Not Reco	mmended					



A CAUTION: DO NOT OVER TIGHTEN SWITCH HARDWARE WHEN INSTALLING!



** **WARNING**: Do not exceed power rating (Watt = Voltage X Amperage). Permanent damage to sensor will occur.

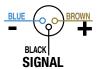
*QD = Quick Disconnect; Male coupler is located 6" [152mm] from sensor,

Female coupler to flying lead distance is 197" [5m] also see Cable Shielding specification above

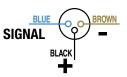


REPLACEMENT OF QD SWITCHES MANUFACTURED BEFORE JULY 1, 1997: It will be necessary to replace or rewire the female end coupler.









Reed Switch Life Expectancy: Up to 200,000,000 cycles (depending on load current, duty cycle and environmental conditions)

†Shielded from the female quick disconnect coupler to the flying leads. Shield should be terminated at flying lead end.

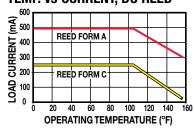
^{§§} Maximum current 250mA (not to exceed 3VA) Refer to Temperature vs. Current graph and Voltage Derating graph



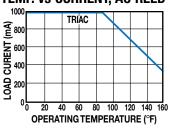
[§] Maximum current 500mA (not to exceed 10VA) Refer to Temperature vs. Current graph and Voltage Derating graph

PERFORMANCE

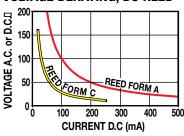
TEMP. vs CURRENT, DC REED



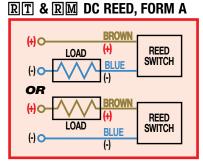
TEMP. vs CURRENT, AC REED



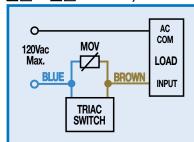
VOLTAGE DERATING, DC REED



WIRING DIAGRAMS



CT & CM AC REED, TRIAC



INSTALLATION INFORMATION



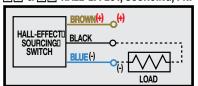


FACE OF THE SWITCH INDICATES THE SENSING **SURFACE AND** MUST FACE TOWARD THE MAGNET.

BT & BM DC REED, FORM C



TT & TM HALL-EFFECT, SOURCING, PNP



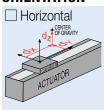


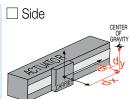
COMPILE APPLICATION REQUIREMENTS

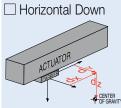
APPLICATION DATA WORKSHEET

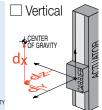
Fill in known data. Not all information is required for all applications

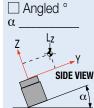
ORIENTATION

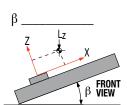












☐ Load attached to carrier OR ☐ Load supported by other mechanism

DISTANCE FROM CENTER OF CARRIER TO LOAD CENTER OF GRAVITY

inch (U.S. Standard)

millimeter

STROKE LENGTH

inch (SK)
(U.S. Standard)

millimeters

Mz
Fy
My
MX

Fz

BENDING MOMENTS M_X _____APPLIED TO CARRIER M_V _____

in.-lbs. (U.S. Standard)

N-m M_Z ______

PRECISION

Repeatability

☐ inch ☐ millimeters

NOTE: If load or force on carrier changes during cycle use the highest numbers for calculations

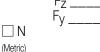
LOAD _____ kg.



☐ Ibf.
(U.S. Standard)

Reverse Parallel

Inline



OPERATING ENVIRONMENT

Temperature, Contamination, etc.

MOVE PROFILE

Move Distance _

 \square inch \square millimeters

Dwell Time After Move_____

Max. Speed

MOVE TIME

per minute

NO. OF CYCLES

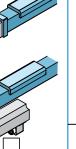
☐ sec

(U.S. Standard)

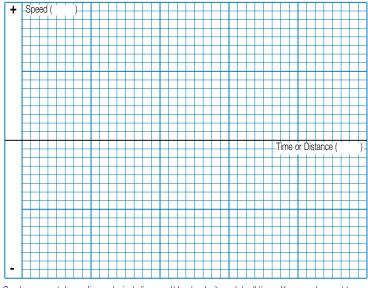
☐ in/sec ☐ mm/sec

per hour





MOTION PROFILE



Graph your most demanding cycle, including accel/decel, velocity and dwell times. You may also want to indicate load variations and I/O changes during the cycle. Label axes with proper scale and units.



USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com OR... CALL TOLOMATIC 1-800-328-2174 with the above information. We will provide any assistance needed to determine the proper MX actuator for the job.

FAX 1-763-478-8080

CONTACT INFORMATION

Name, Phone, Email Co. Name, Etc.



SELECTION GUIDELINES

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that you contact Tolomatic or a Tolomatic Distributor for assistance in selecting the best actuator for your application. The following overview of the selection guidelines are for educational purposes only.

CHOOSE ACTUATOR SIZE

Choose an actuator that has the thrust, speed and moment load capacity to move the load. Use the Critical Speed graphs (page BCS_4-5) for the screw and the Moment and Load Capacity table (pg. BCS_9) for the actuator.

COMPARE LOAD TO MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments Mx, My, and Mz applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated. its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at the end of the stroke is required for extended actuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (pg. BCS_9) for the actuator consider:

1) Higher capacity bearing style

- 2) A larger actuator size
- 3) Auxiliary carrier
- 4) External guide system

CALCULATE LOAD FACTOR LF

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor (LF) must not exceed the value of 1.

$$L_{\text{F}} = \frac{Mx}{Mx_{\text{max}}} + \frac{My}{My_{\text{max}}} + \frac{Mz}{Mz_{\text{max}}} + \frac{Fy}{Fy_{\text{max}}} + \frac{Fz}{Fz_{\text{max}}} \leq 1$$

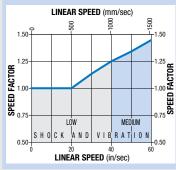
If LF does exceed the value of 1. consider the four choices listed in step #2.

ESTABLISH YOUR MOTION PROFILE TAND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speeddecel) profile. Now calculate the maximum acceleration and deceleration rates of the move. Speed should not exceed critical speed value as shown on graphs (page BCS_4-5) for the screw/nut combination cho-

SPEED FACTOR

FOR APPLICATIONS WITH HIGH SPEED OR SIGNIFICANT SHOCK AND VIBRATION: Calculated values of loads and bending moments must be increased by speed factor from the graph below to obtain full rated life of profiled rail bearing system.



sen. Also, do not exceed safe rates of dynamic inertia moments determined in step #3.

SELECT THE LEAD

Based on the application requirements for accuracy, backlash, quiet operation, life, etc. select the appropriate lead screw type (Acme screw with a solid nut or ball screw with a standard or antibacklash nut) and the pitch (lead). For additional information on screw selection, consult "Which Screw? Picking the Right Technology" (#9900-4644) available at www.tolomatic.com.

► SELECT MOTOR (GEARHEAD IF NECESSARY) AND DRIVE

To help select a motor and drive, use the sizing equations located in the Engineering Resources sec-[ENGR] to calculate the application thrust and torque requirements. Refer to Motor sections [MRV] & [MRS] to determine the motor and drive.

DETERMINE TUBE SUPPORT/ MOUNTING PLATE REQUIREMENTS

- Consult the Support Recommendations graph for the model selected (page BCS 8)
- Cross reference the application load and maximum distance between supports
- Select the appropriate number of tube supports, and mounting plates if required for motor and adapter clearance.

CONSIDER OPTIONS

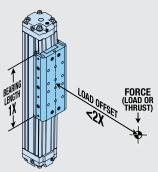
- Choose metric or inch (US conventional) load mounting.
- Switches Reed, Solid State PNP or NPN, all available normally open or normally closed
- FL Floating mount bracket - used when lack of parallelism occurs between the actuator and an externally quided and supported load

sizeit.tolomatic.com

for fast, accurate actuator selection



S SOLID BEARING 2:1 RULE



For applications using BCS actuator, binding or interrupted motion may occur if the load offset is equal to or greater than twice the bearing length (1X).

LOAD OFFSET is defined as: the distance from the applied force (or the load center of gravity) to the centerline of the carrier.

If the load offset cannot be changed consider:

- 1.) Higher capacity bearing style
- 2.) Larger Bore Cylinder
- 3.) Auxiliary Carrier
- 4.) Add External Guides



BASE MODEL SPECIFICATIONS

BCS 20 BN02 SK45 RPL1

ORDERING

OPTIONS SPECIFICATIONS

DC18 KT2 MP2



MODEL TYPE

BCS BCS Series US Conventional Screw Drive

SIZE

10. 15. 20

NUT/SCREW CONFIGURATION

INCH MODELS	METRIC
(US Conventional)	Models†
SOLID NUT /	SOLID NUT /
PITCH (turn/in)	LEAD (mm/turn)
SN01 SN02 SNA02 SN05	SN25 SN12
BALL NUT /	BALL NUT /
PITCH (turn/in)	LEAD (turn/in)
BN02 BNL02 BN05 BNL05 BN08 BNL08	BN05 BNL05 BN08 BNL08

† The metric version provides metric tapped holes for mounting of the load to the carrier and of the actuator to mounting surfaces

STROKE LENGTH & MOUNTING TYPE

SK __.__ Stroke, enter desired stroke length in inches

SM† __._ Stroke, enter desired stroke length in millimeters

NOTE: Actuator mounting threads and mounting fasteners will be either inch or metric; depending on how stroke length is indicated.

SK = inch mounting **SM** = metric mounting

MOTOR MOUNTING / REDUCTIONS

(must choose one)

LMI In-Line mounting

LME23 Ext. shaft for RP & 23 frame motor **LME34** Ext. shaft for RP & 34 frame motor

LME40 Ext. shaft for RP & 40 frame motor **LMX Extended shaft - old style (see note)

**For replacement actuators with extended motor shafts purchased prior to 6/24/02 use LMX

A motor size and code must be selected when specifying a reverse-parallel mounting configuration.

RPL1 1:1 Reverse-Parallel mount left

RPR1 1:1 Reverse-Parallel mount right

RPB1 1:1 Reverse-Parallel mount bottom

RPT1 1:1 Reverse-Parallel mount topRPL2 2:1 Reverse-Parallel mount left

RPR2 2:1 Reverse-Parallel mount right

RPB2 2:1 Reverse-Parallel mount bottom

RPT2 2:1 Reverse-Parallel mount top

AUXILIARY CARRIER

DC _ Auxiliary Carrier, then center-to-center spacing desired in in inches (**SK**) or millimeters (**SM**).

(Same unit of measure as stroke length is required)
Center-to-center spacing between carriers
adds to overall length of the actuator, this
distance will not be subtracted from stroke
length specified in the previous step.

A

Not all codes listed are compatible with all options.

Use the Sizing Software to determine available options and accessories based on your application requirements.

SWITCHES

RM_ Reed Switch (Form A) with 5-meter lead/QD (quick-disconnect), & quantity

RT_ Reed Switch (Form A) with 5-meter lead, and quantity desired

BM_ Reed Switch (Form C) with 5-meter lead/QD, and quantity desired

BT_ Reed Switch (Form Ć) with 5-meter lead, and quantity desired

KM_ Hall-effect Sinking Switch with 5-meter lead/QD, and quantity desired

KT_ Hall-effect Sinking Switch with 5-meter lead, and quantity desired

TM_ Hall-effect Sourcing Switch with 5-meter lead/QD, and quantity desired

TT_ Hall-effect Sourcing Switch with 5-meter lead, and quantity desired

CM_ TRIAC Switch with 5-meter lead/QD, and quantity desired

CT_ TRIAC Switch with 5-meter lead, and quantity desired

SUPPORTS AND MOUNTING PLATES

(both may be selected)

TS _ Tube Supports plus quantity desired MP2 Mounting Plates, 2 in kit

FLOATING MOUNT

FL Floating Mount Bracket

FOOD GRADE LUBRICATION

LUB Grease, Food/Drug

	FIELD RETROFIT KITS												
ITEM	BCS10_SK	BCS15_SK	BCS20_SK	BCS10_SM	BCS15_SM	BCS20_SM							
Tube Supports	4510-1010	4515-1010	4520-1010	4510-1010	4515-1010	4520-1010							
Mounting Plates	0910-9133	0915-9135	0920-9038	0510-9105	0515-9138	0520-9105							



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"Foldout" Brochure #9900-9075



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"Foldout" Brochure #9900-9076

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