





**Electric Actuators & Small Robots for Smart Industrial Automation** 





## Advancing into a new Era switching Air to EleCylinder

Designed to move between two points just like Air Cylinder Speed / Acceleration / Deceleration can be set in just 5 minutes.







Slider Type

EC-S

Rod Type EC-R



Cylinder Type



EC-S□R





Simple model selection & operation

- Start and end points can be set at any value.
- **A** (Acceleration), **V** (Velocity), **D** (Deceleration), A.V.D. can be adjusted individually.
- Few maintenance parts
- Stable velocity. Cycle time can be reduced.
- Long service life.

## Next Generation RoboCylinder RCP6/RCS4

From an abundant lineup of 92 RCP6 models with pulse motor or 54 RCS4 models with servo motor, you can find one that is most suitable for your needs.









Rod Type



Radial Cylinder Type Wide Radial Cylinder Type RCP6/RCS4-RRA RCP6/RCS4-WRA



Table Type RCP6/RCS4-TA



Cleanroom Type RCP6CR/RCS4CR



Dust/Splash-Proof Type

Slider Type RCP6/RCS4-SA

Wide Slider Type RCP6/RCS4-WSA

RCP6(S)/RCS4 SERIES SIDE-MOUNTED MOTOR TYPE

RCP6/RCS4-RA

Equipped with high-resolution battery-less absolute encoder as standard.

- Improved positioning repeatability:
- ±10μm (Standard Type), ±5μm (High-Precision specification).
- PowerCon compatible.
- Built-in Controller (RCP6S) can be selected for every RCP6 type.
- Cleanroom and Dust/Splash-Proof specification series available.

\*Built-in Controller Type (RCP6S) is available



Slider Type RCP6/RCS4-SA



Wide Slider Type RCP6/RCS4-WSA



**Rod Type** RCP6/RCS4-RA



Radial Cylinder Type RCP6/RCS4-RRA



Wide Radial Cylinder Type RCP6/RCS4-WRA



Table Type RCP6/RCS4-TA

## Servo Press Compatible RoboCylinder with Load Cell

Compact and low-thrust rod type actuator that can even be used for simple pressing. The high-precision position control enables easy adjustment of the push force and the position control, typically difficult for hydraulic equipment. 8 types from a range of 20N - 50000N are available.



Max. 600N RCS3-RA6R









#### Loading repeatability is ±0.5%. Supports traceability. Variety of product groups: 8 models in the lineup. Setting is easy by using a dedicated software.

- Newly developed 3kW motor driver achieved max. Thrust of 5t and max. Speed of 220mm/sec.
- With Battery-less Absolute Encoder as Standard. High Payload Rod Types without Load Cell also available: max. Payload of 1/0.6t (horizontal/vertical).





Max. 50000N RCS3-RA15R RCS3-RA20R

## **Wrist Unit**

IAI's unique design makes the parts light and compact. Low cost compared to 6-axis

articulated robots. Orthogonal axes and interpolation

commands are possible.



Medium Type WU-M

## RoboCylinder



These affordable, highly precise and highly rigid actuators have 1/5th the running cost of a pneumatic system

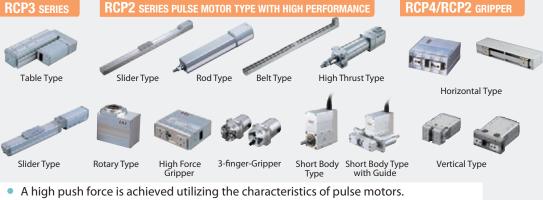
RoboCylinder is high-performance electric actuator equipped with a ball screw, linear guide, and servo motor. These next-generation actuators have multi-point positioning capability as well as the ability to change speed and acceleration, unlike anything seen with air cylinders.



- Battery-less absolute encoder as standard equipment.
- By using a PowerCon, it has 1.5 times higher speeds and double the payload compared to traditional models.

# Radial Load OK Slider Type Rod Type [Radial Cylinder] Side-mounted Motor Type

 By using a PowerCon, it has 1.5 times higher speeds and double the payload compared to traditional models.



• An abundance of sizes and variations is available to meet a wide range of applications.

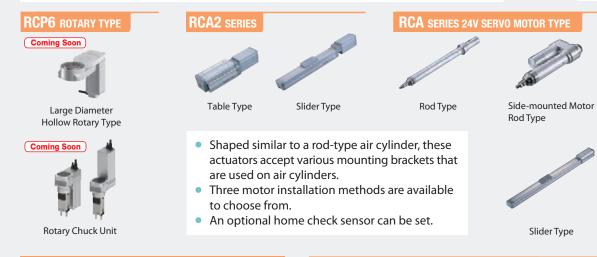
## Slim Long Stroke Type High-force Type • Equipped with a Battery-less

- Equipped with a Battery-less Absolute Encoder.
- High Rigidity
- Slim High-force Type:
   Flat Shape with height of 39mm.
- Long Stroke Type: max. opening/ closing stroke of 260mm

Rod Type with Guide

Side-mounted Motor

Slider Type



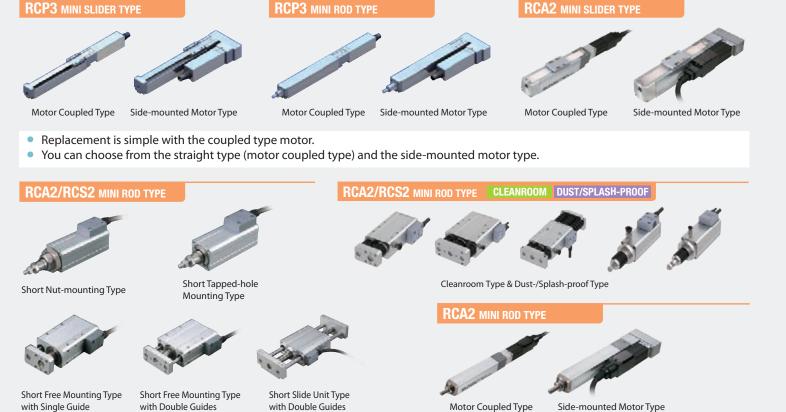


- Equipped with a servo motor, these actuators support high loads and long strokes.
- When an XSEL controller is used, you can combine three or more axes.
- Compatible with ProfiBus, DeviceNet, CC-Link, and other field networks.

## Mini RoboCylinder



Next-generation electric actuators, the solution for space constrained applications



- You can choose between the slim motor coupled type and the short free mounting type, that has significantly reduced in length.
- You can choose between built-in guide type which allows for increased rigidity and straightness, or the external guide type which has significantly been reduced in size.

#### RCA2/RCS2 MINI TABLE TYPE



**Short Compact Type** 



Short Wide Type



Short Flat Type

#### RCP3/RCA2 MINI TABLE TYPE







Side-mounted Motor Type

- The built-in guide allows the actuator to hold overhung loads.
- You can choose between the compact short type and the motor coupled type with longer stroke.

#### **RCD** MICRO CYLINDER



- The smallest in the industry with a cross-section size of 12mm.
- The built-in encoder allows position control.

## **Solenoid** Gripper

Compact and lightweight electric gripper that fits in the palm of the hand.

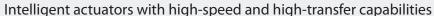
The price is as low as an air chuck. Opening and closing of the fingers are operated simply by ON/OFF signals of single wiring.

Continuous retention is possible while still in the gripping or release state.



GRS-M

## Single-axis Robots





Slim Belt-drive Type



## Cleanroom Types

**Rotary Type** 

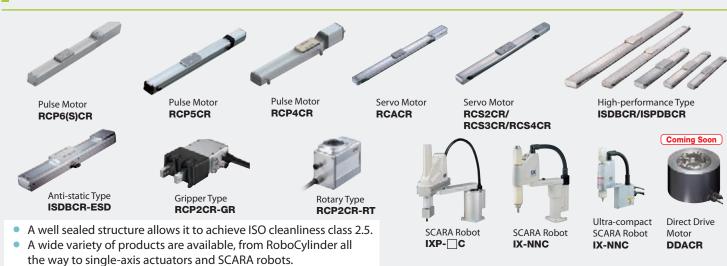
Dedicated cleanroom types conforming to ISO cleanliness class 2.5 \*

**Nut Rotational Type** 

\* ISO Standard 14644-1:2015 (according to class 4 of previous ISO Standard 14644-1:1999)

Many variations are available to meet diverse applications.

The guide is integrated with the base for the linear actuators.



## Splash-proof/Dust-proof Types

These actuators offer protection conforming to IP54~IP67, and are a desirable solution when operated in adverse environments.



- These actuators handle environments with extreme dust or water splashes.
- Many variations are available to meet diverse applications.

## IXP Series I PowerCon Scara Robots

All models come standard with battery-less absolute encoders

#### POWERCON SCARA ROBOT ARM LENGTH 180/250/350/450/550/650mm



Standard Type



**Gripper Type** 





Splash-proof/ Cleanroom Type **Dust-proof Type** 

- All models come standard with battery-less absolute encoders.
- The encoder resolution has increased to 10 times that of the existing IXP.
- The cost of IXP is around half of the traditional models.
- Lighter than conventional models.
- The regular cycle time is about 60% shorter than conventional cartesian robots.
- Added 3-axis specification, 4-axis with gripper specification.
- Equipped with optimal speed and acceleration/deceleration settings.

## **IX Series I Scara Robots**

The IX SCARA robots feature high performance and functionality



**Battery-less Absolute Encoder** 

No Price Increase. No Going Back to Incremental.

No Battery, No Maintenance, No Homing, and

#### SCARA ROBOT ARM LENGTH 120/150/180/250/350/500/600/700/800mm

















High-speed Type

Wall Type

Ceiling Type

- Achieves high speeds, payload and precision.
- Easy programming makes these actuators much more user-friendly.
- It supports a wide variety of arm lengths, ranging from 120mm to 800mm.

## **IXA Series I High-power Scara Robots**

New IXA SCARA robots with servo motor and battery-less absolute encoder

Battery-less Absolute Encoder No Battery, No Maintenance, No Homing, and No Price Increase. No Going Back to Incremental.

#### HIGH-POWER SCARA ROBOT ARM LENGTH 300/450/600mm







Standard and High-speed Type (Vertical axis stroke:: 150/180/330mm)

- Fastest cycle times.
  - (Standard cycle time of high-speed type: 0.26s)
- Achieves a low price.
- Low vibration, accurate positioning.
- Equipped with a Battery-less Absolute Encoder as standard.
- Patent pending: Mechanical structure / features
- Standard type / High-speed type are available.

## TTA Series | Tabletop Robots

Improved tabletop robots for cell productions, R&D applications, and more

#### **Gate Type**





3-axis Specification



4-axis Specification





2-axis Specification



3-axis Specification



4-axis Specification

- Every model equipped with battery-less absolute encoder as standard.
- AC Servo Motor specification added to the series.
- Max. payload: X-axis: 30kg Z-axis: 15kg (AC servo motor), Max. speed: XY-axis: 1200mm/s Z-axis: 40mm/s (AC servo motor)
- Improved positioning repeatability: ±0.005mm (AC servo motor) /±0.01mm (Pulse motor spec)
- The SEL Program Generator eliminates the tedious work of program creation.



## **DDA Direct Drive Motors**

Coming Soon

High speed/payload/precision, easy control, and compact: A direct drive motor that achieved high cost-performance.



Slim Type



High Torque type

- Positioning repeatability ±0.00103 degree (±3.7s), Index accuracy  $\pm$  0.00833 degree ( $\pm$ 30s) with SCON-CB & High resolution type.
- Maximum speed of 1800°/s and acceleration/deceleration of 6.0G can make faster positioning time possible.
- Standard or Cleanroom specification (Hollow bore: Ø52mm), Slim or High-torque types in lineup. Flange option is available.

## **Cartesian Robots**

Pre-configured cartesian robots that reduce installation and setup times







Y-axis Base Mount Type



Y-axis Slider Mount Type XYS



Z-axis Base Mount Type



Y-axis Base Mount Type



Y-axis Slider Mount Type



**Gantry Type** XYG

ICSB3/ICSPB3 3-AXIS CONFIGURATION



XYB + Z-axis Type B \_\_\_\_\_



XYG + Z-axis Type G\_\_\_\_\_

#### **ICSPA4** 4-AXIS CONFIGURATION



**ICSPA6** 6-AXIS CONFIGURATION



- Many variations are available to support 2 to 6-axis configurations.
- The multi-slider types (ICSPA4/ICSPA6) let you reduce space and cycle time.
- High resolution Battery-less Absolute Encoder is available.
- Any models can be customized to meet your specific needs.

## Cartesian RoboCylinder

Multi-axis RoboCylinder RCP2/RCP6/RCS2 kits at a reasonable price

## IK2-P/IK2-S 2-AXIS CONFIGURATION



Y-axis Base Mount Type





Z-axis Base Mount Type

#### IK2-P6 2-AXIS CONFIGURATION



Y-axis Base Mount Type



Z-axis Base Mount Type

#### IK3-P/IK3-S 3-AXIS CONFIGURATION



Y-axis + Z-axis Base Mount Type XYB+Z



IK3-P6 3-AXIS CONFIGURATION

Y-axis + Z-axis Base Mount Type XYB+Z

#### IK4-P6 4-AXIS CONFIGURATION



Y-axis Base Mount Type + ZR (Vertical/Rotation) Unit Type

- IK-P series: RCP2 combinations based on 24 VDC pulse motor. IK-S series: RCS2 combinations based on 230 VAC servo motor.
- IK-P6 series: RCP6 combinations based on 24 VDC pulse motor with battery-less absolute encoder and high-output driver specification (PowerCon).

## **Controllers**

A wide variety of operational patterns to fit your specific needs



Free Ladder Programming Software is available for our controller with PLC function

#### POSITION CONTROLLER

#### PSEP



For RCP2/RCP3



For RCA/RCA2





ACON CB DCON CB SCON CB SCON-CAL

- 3-position controllers.
- Use the same signals as air-cylinder solenoid valves.
- Standard and dust-proof specifications are available.
- The dust-proof specification has a protective structure conforming to IP53, allowing it to be installed outside the control panel.

#### PCON-CB (PowerCon)

For RCP6/5/4/3/2



For RCA/



For RCD



For RCS2/3/4 Single-axis (SCON-CB/LC)



For RCS2/3/4 Single-axis/ Cartesian

- PowerCon archives 150% more output compared to the traditional models. It supports RCP5 etc. with a battery-less absolute encoder.
- Up to 512 positions can be set.
- ProfiBus, DeviceNet and other field networks can be supported.
- SCON-CB comes with vibration control function.
- SCON-LC and MSEP-LC with PLC function via LC ladder software.

#### MCON

For RoboCylinder, CON Series 8-axis Type



MSEP For RoboCylinder. 8-/6-axis Type

(MSEP-C/LC)



RCON For RoboCylinder, CON Series 8-/16-axis Type



MS CON SCON Controller, 6-axis Type



- Supporting RCP6 with battery-less absolute encoder.
- Supporting PowerCon (Highoutput driver), and Mini Cylinder.
- Supporting PowerCon (High-output driver), and Mini Cylinder (MSEP-C/LC).
- Module based network controller with gateway, axis driver, SCON extension and simple absolute unit (RCON).
- For RCS2/3/4 and single-axis robot, combined 6 controllers into 1 controller.
- Supporting various field networks.

#### **PROGRAM CONTROLLER**





For RCP2/RCP3 For RCA/RCA2



Single-axis



For RCS2/RCS3/RCS4





#### MSEL



For RCP6/5/4/3/2/ PowerCon SCARA

- PSEL/ASEL/SSEL controllers support interpolated operation and are used to set 1 or 2 axes.
- XSEL controllers can operate up to 8 axes.
- All controllers support ProfiBus, DeviceNet and other field networks.

## Teaching Pendants

Programming points have never been easier Compatible with Safety Category



**Touch Panel Teaching Pendant** for Position Controllers and **Program Controllers** 

**TB-02** 



**Touch Panel Data Setter** (for EleCylinder also with Wireless Function)

**TB-03** 





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